



XYT STACKED SYSTEM

ASME-NGNN-04-0365-0355xx

VULCANO2 XYT (DXR+) with AccurET VHP

Data sheet

Version 2.1

ETEL

AXIS DESIGNATION			
Number of controlled axes	4		
Axes name	X1-X2 (bottom axis)	Y (top axis)	Theta
Thrust transmitter: DD (direct drive) or ID (indirect drive)	DD	DD	DD

TESTING CONDITIONS	UNIT			
Position controller	-	VHP 100 10/30 Arms	VHP 100 10/30 Arms	VHP 100 10/30 Arms
Motion controller	-	UltimET		
Rated payload (1)	kg	2		
Rated inertia (1)	kg.m ²	-	-	0.018
Rated input voltage	VDC	96	96	96
Tool point position	mm	301 mm above bottom surface		
Ambient temperature	°C	22 ±1		
Isolation system	-	QuiET		

DIMENSIONAL DATA	UNIT			
Width	mm	765		
Length	mm	781		
Height	mm	281		
Total stroke	mm	365	355	Infinite
Moving mass (without payload)	kg	35.3	13.3	-
Total mass (without payload)	kg	161		
Rotor inertia (without payload)	kg.m ²	-	-	0.004

FORCE / TORQUE CAPABILITIES (2)	UNIT			
Peak force / torque	N or Nm	1970	594	7.87
Continuous force / torque	N or Nm	458	162	1.74
Standstill force / torque	N or Nm	346	122	1.32
Max. detent force / torque (average to peak)	N or Nm	34	12	0
Static friction (maximal value)	N or Nm	10.7	11.8	1
Dynamic friction (maximal value)	N/(m/s) or Nm/(rad/s)	23.5	28.7	0.03

LOAD CAPACITIES	UNIT			
Maximum payload	kg	30		

DYNAMIC PERFORMANCE	UNIT			
Duty cycle	%	30	50	10
Maximum speed	m/s or rad/s	1.2	1.2	30
Maximum acceleration	m/s ² or rad/s ²	25	25	180
Typical position stability at 2 kHz	nm or arcsec	±2	±2	±0.02

ACCURACY	UNIT			
Positioning accuracy (without mapping)	µm or arcsec	±10	±30	±30
Positioning accuracy (with mapping)	µm or arcsec	±1	±1	±3
Bidirectional repeatability	µm or arcsec	±0.25	±0.25	±2
Horizontal straightness / radial runout	µm	±1.5	±3.5	±3.5
Vertical straightness / total axial error at 0 [mm] radius	µm	±3	±5	±3
Orthogonality (without gantry correction)	arcsec	±15		-
Roll	arcsec	±20	±25	-
Pitch	arcsec	±20	±60	-
Yaw	arcsec	±1.5	±10.0	-

WORKING ENVIRONMENT			
Clean room compatibility (3)	ISO 2		

ELECTRICAL SPECIFICATIONS (2)		UNIT	X (bottom axis)	Y (top axis)	Theta
Motor type	-		Ironcore	Ironcore	Toothless
Motor model	-		LMG10-070-3SB-H01	LMG10-050-3TB-209	TTB0126-030-3NA-239
Number of phases	-		3	3	3
Kt Force constant	N/Arms or Nm/Arms		41.7	23.4	1.23
Ku Back EMF constant (4)	Vrms/(m/s) or Vrms/(rad/s)		25.2	14.2	0.712
Km Motor constant	N/√W or Nm/√W		30.4	24.6	-
R20 Electrical resistance at 20°C (4)	Ohm		1.25	0.61	10.50
L1 Electrical inductance (4)	mH		8.89	3.8	2.65
Ip Peak current	Arms		30.0	30.0	6.90
Ic Continuous current	Arms		5.69	7.22	1.47
Is Standstill current	Arms		4.31	5.47	1.11
vs Standstill speed	mm/s or rad/s		0.14	0.14	0.0016
Um Max. input voltage	VDC		100	100	100
Pc Max. cont. power dissipation	W		123	62.5	41.9
2τp Magnetic period	mm		32	32	-
2p Number of poles	-		-	-	28

ENCODER CHARACTERISTICS		UNIT			
Encoder and signal type	-		Optical - incremental	Optical - incremental	Optical - incremental
Output signal	-		1 Vpp	1 Vpp	1 Vpp
Signal period or line count	μm or period/turn		4	4	18 000
Reference mark	-		One	One	One
Power supply	V		5	5	5

TYPICAL MOVE AND SETTLE TIMES		UNIT			
Move 1: 10 μm within ±100 nm window	ms		40	40	-
Move 2: 25 mm within ±100 nm window	ms		125	125	-
Move 3: 80 mm within ±100 nm window	ms		170	170	-
Move 4: 1 deg within ±40 μdeg	ms		-	-	100
Move 5: 180 deg within ±40 μdeg	ms		-	-	500

GUIDING ELEMENTS				
Type		Ball bearing	Ball bearing	Crossed roller bearing

MATERIAL AND FINISH				
Baseplate		Granite	Stainless steel	Aluminium alloy
Carriage		Stainless steel	Stainless steel	Stainless steel

According to the Machinery Directive 2006/42/EC, the system presently described falls into the "partly completed machinery" category and fully complies with it as long as the system is operated according to the working conditions described in the corresponding manual. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the system is used in an improper way.

Notes: The specifications given may be mutually exclusive. Unless stated otherwise, all measurements are made within the testing conditions.

- (1) Payload can be assimilated to a cylinder of diameter 270 mm, 19 mm thick, weighting 2 kg. Inertia is expressed with respect to the center of gravity of the payload, Z being the axis of rotation.
- (2) Tolerances on electrical parameters are available on request.
- (3) Under horizontal laminar flow conditions at 0.45 m/s along X axis. Measured at 12 mm above customer mobile interface. Contact ETEL for more details.
- (4) Terminal to terminal.